

More Precision

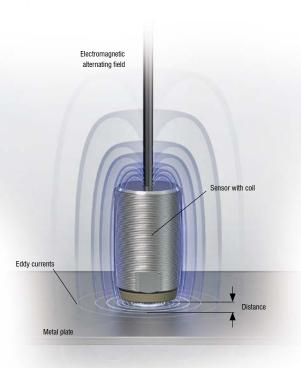
eddyNCDT // Eddy current sensors for displacement and position



2

eddyNCDT





Measuring principle

The eddy current principle occupies a unique position amongst inductive measuring methods. The measuring principle is based on the extraction of energy from an oscillating circuit. This energy is required for the induction of eddy currents in electrically-conductive materials. Here, a coil is supplied with an alternating current, causing a magnetic field to form around the coil. If an electrically conducting object is placed in this magnetic field, eddy currents are induced which form a field according to Faraday's induction law.

This field acts against the field of the coil, which also causes a change in the impedance of the coil. The impedance can be calculated by the controller by looking at the change in the amplitude and phase position of the sensor coil.

Eddy current sensors

For many years, Micro-Epsilon has been a pioneer in displacement measurement using eddy current technology. Eddy current sensors from Micro-Epsilon are designed for non-contact measurement of displacement, distance, position, oscillation and vibrations. Eddy current sensors from Micro-Epsilon are extremely robust and precise.

Advantages

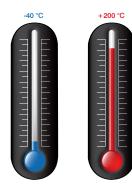
- Wear-free and non-contact measurement
- High precision and resolution
- High temperature stability
- Ferromagnetic and non-ferromagnetic materials
- For demanding, industrial environments: dirt, pressure, temperature
- Fast measurements up to 100kHz

eddyNCDT: Robust sensors with unmatched precision

Eddy current sensors from Micro-Epsilon are often used in applications where harsh ambient conditions are present and where maximum precision is required. Immunity to dirt, pressure and extreme temperature are distinctive features. The many designs of eddy current sensors enable engineers to select the optimal sensor for their particular application.

Custom sensors for automation and OEMs

Application examples are often found where the standard versions of the sensors and the controller are performing at their limits. For these special tasks, the measuring systems can be modified according to a customer's specific individual requirements. Changes requested include, for example, modified designs, target calibration, mounting options, individual cable lengths, modified measuring ranges or sensors with integrated controller.



Ideal for temperature fluctuations

- Active temperature compensation of sensor, cable and controller
- Temperature range -40°C to 200°C and higher



Robust and reliable sensors IP67

Resistant to oil, dust & dirt

Pressure-resistant models up to 2,000 bar



Comprehensive product range

- More than 400 sensor models
- Miniature sensors smaller than 2mm
- Custom sensors and OEMs

| Eddy current sensor with integrated electronics Page 4 - 5 eddyNCDT 3001 • • Measuring range 2/4mm • • Resolution 4μm • • Frequency response 5kHz • | Compact eddy current sensor systemPage 6 - 9eddyNCDT 3005• Measuring range 1 - 6mm• Resolution $\geq 0.5\mu$ m• Frequency response 5kHz |
|---|--|
| Robust eddy current sensor system Page 10 - 13 eddyNCDT 3010 • • Measuring range 0.5 - 15mm • • Resolution ≥ 0.025µm • • Frequency response 25kHz • | Flexible eddy current sensor systemPage 14 - 17eddyNCDT 3100 \blacksquare • Measuring range 0.5 - 15mm• Resolution $\ge 0.025 \mu m$ • Frequency response 25kHz |
| High precision eddy current sensor system Page 18 - 25 eddyNCDT 3300 ■ ■ Measuring range 0.4 - 80mm ■ ■ Resolution ≥ 0.02µm ■ ■ Frequency response up to 100kHz ■ | Turbocharger speed sensors turboSPEED DZ140Page 26 - 29• Measuring range 0.5 - 1mm • Speed range 200 RPM to 400,000 RPM • Operating temperature up to 285°C• Page 26 - 29 |
| Spindle Growth SystemPage 30 - 31eddyNCDT SGS4701 \blacksquare • Measuring range 500 μ m \blacksquare • Resolution $\ge 0.5\mu$ m \blacksquare • Frequency response 2kHz | Application examples/AccessoriesPage 32 - 33Technical informationPage 34 - 39 |

4 Compact eddy current sensors with integrated electronics

eddyNCDT 3001



- Compact M12 sensor design with integrated controller

- Frequency response 5kHz (-3dB)
- Sensor for ferro- and nonferromagnetic targets
- Temperature compensation up to 70°C
- Easy to use (plug & play)
- Robust design to IP67
- Ideal for OEM applications

Robust miniature eddy current sensor

The eddyNCDT 3001 is a completely new high performance eddy current sensor platform. Although it is a similar size to currently available proximity and inductive sensors, the measuring performance is much greater. With integrated electronics including active temperature compensation, the sensor provides high measurement stability even in fluctuating temperature environments. Combined with an extremely competitive pricing structure, this is an ideal OEM solution. The device can be supplied in single quantities for evaluation and can be modified if required for higher volume applications.

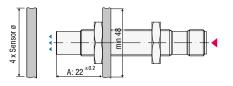
The sensor is factory calibrated with both ferrous and non-ferromagnetic materials, which eliminates the need for onsite linearisation of the sensor. The robust construction, combined with true eddy current measurement principle, enables measurements in harsh industrial environments (oil, pressure, dirt). Additionally, the eddy NCDT 3001 is also suitable for offshore and marine applications (saltwater resistant).

Installation instructions

The relative size of the measurement object to the sensor and the position of the mounting nut have effects on the linearity deviation for eddy current sensors.

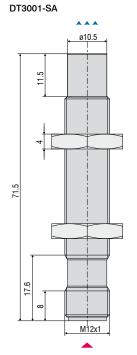
Please note:

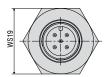
- Depending on the sensor model, the measurement object geometry shall be 4 times the sensor diameter.
- The mounting nut should not exceed the indicated dimension A.



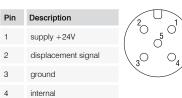
| Model | DT3001-U2A-SA | DT3001-U2M-SA | DT3001-U4A-SA | DT3001-U4M-SA | DT3001-U4A-Cx | DT3001-U4M-Cx |
|--|--|---------------|---------------|---------------|---------------------|---------------------|
| Measurement object 1) | aluminium | steel | aluminium | steel | aluminium | steel |
| Measuring range | 2n | nm | | 4m | าทา | |
| Offset distance | | | 0.4 | mm | | |
| Linearity | | | 28 | um | | |
| Resolution ²⁾ | | | 4µ | ım | | |
| Frequency response | | | 5kHz (| -3 dB) | | |
| Temperature stability | | | 0.03% F | SO/°C | | |
| Temperature compensation range | | | 0°C | +70°C | | |
| Ambient temperature | | | 0°C | +70°C | | |
| Installation | | | unshi | elded | | |
| Recommended measurement object geometry (flat) | | | 48r | nm | | |
| Connection | | connector | 5-pin M12 | | integrated cable, 5 | -pin, length 3/6/9m |
| Output | 0.5 9.5V 0.5 4.5V | | | | | . 4.5V |
| Power supply | 12V 32V | | | | | |
| Protection class | IP67 (connected) IP67 | | | | 67 | |
| Weight | 60g (3m) 25g 100g (6m) 140g (9m) | | | | (6m) | |

FSO = of full scale output ¹⁾ Steel: ST37 DIN 1.0037 / aluminium: AlCuMgPb3.1645 ²⁾ Static resolution (16Hz) at midrange





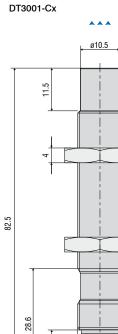
Pin assignment 5-pin M12-connector



0

internal

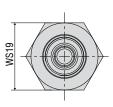
5



12

ø4.3

M12x1



Pin assignment

| Colour | Description |
|--------|---------------------|
| brown | supply +24V |
| green | displacement signal |
| white | ground |
| yellow | internal |
| grey | internal |



5

Dimensions in mm, not to scale.

eddyNCDT 3005



- Compact and robust design
- Temperature compensation up to 180°C
- High precision measurement accuracy
- High frequency response
- Sensor for ferro- and non-ferromagnetic targets
- Easy to use (plug & play)
- Perfect for machine integration

Eddy current displacement measurement

Eddy current sensors from Micro-Epsilon are designed for displacement, distance, movement and position measurements, but also for detecting oscillations and vibrations. Non-contact operating eddy current sensors from Micro-Epsilon are renowned for their extreme precision, and are even used for micrometre-accuracy measurements.

Robust eddy current measurement system

The eddyNCDT 3005 is a new, powerful eddy current measurement system for fast, high precision displacement measurements. The system comprises a compact controller, a sensor and an integrated cable and is factory-calibrated for ferromagnetic and non-ferromagnetic materials.

As sensor and controller are temperature-compensated, high measurement accuracies can be achieved even in fluctuating temperatures. The sensors are designed for ambient temperatures up to max. +125°C but can optionally be custom engineered for temperatures from -30°C to +180°C. The measurement system is pressure-resistant up to 10 bar and so is ideally suited to machine integration.

Ideal for integration into plant and machinery

The eddyNCDT 3005 provides ease of use and high measurement accuracy, offering an outstanding price/performance ratio. Therefore, the sensor is ideally suited to OEM integration and mechanical engineering applications. Particularly where pressure, dirt, oil and high temperatures are present, the eddyNCDT 3005 is suitable. Where high volume orders are required, customer-specific designs can be tailored to suit individual requirements.

Multi-channel operation without mutual interference

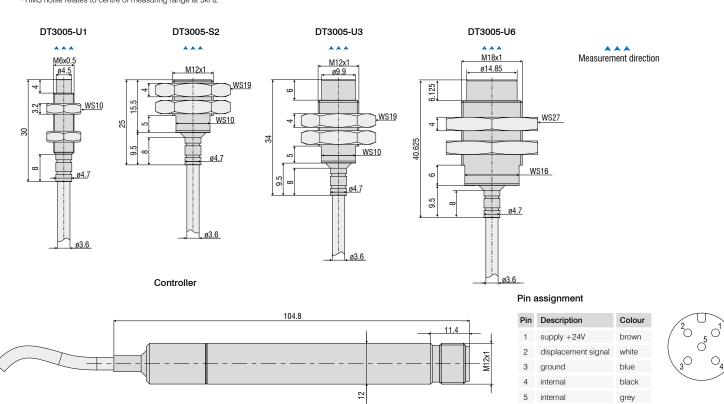
If two or more systems operate next to one another, there is no need for synchronisation. For operating several systems, a new frequency separation is provided, which enables to operate these systems in parallel without influencing one another. Tuning via synchronisation cable is not necessary.



| Model | | DT3005- U1-A-C1 | DT3005- U1-M-C1 | DT3005- S2-A-C1 | DT3005- S2-M-C1 | DT3005- U3-A-C1 | DT3005- U3-M-C1 | DT3005- U6-A-C1 | DT3005- U6-M-C1 | |
|--|------------|--------------------------------------|-------------------------------------|--------------------|--------------------|--------------------|--------------------|--------------------|--------------------|--|
| Measurement object 1) | | aluminium steel | | aluminium | steel | aluminium | steel | aluminium | steel | |
| Measuring range | | 1m | ım | 2m | ım | 3r | 3mm | | 6mm | |
| Offset distance | | 0.1r | mm | 0.2r | 0.2mm 0 | | mm | 0.6 | nm | |
| Linearity | ≤0.25% FSO | 2.5 | um | 5μ | m | 7.5 | iμm | 15µm | | |
| Resolution 2) | ≤0.05% FSO | 0.5/ | um | 1μ | m | 1.5 | iμm | 3µ | m | |
| Repeatability | | | | | ≤0.05 | 5% FSO | | | | |
| Max. sensitivity deviation | | | | | ≤ | 1% | | | | |
| Frequency response | | | | | 5kHz(| (-3dB) | | | | |
| Temperature stability (MMR) | | 0.025% FSO / °C | | | | | | | | |
| Temperature | sensor | | 10°C + 125°C (optional -30°C 180°C) | | | | | | | |
| compensation range | controller | | | | 10°C | .+60°C | | | | |
| Ambient temperature | sensor | -30°C +125°C (optional -30°C 180°C) | | | | | | | | |
| Ambient temperature | controller | | | | -20°C | +70°C | | | | |
| Design | | unshi | elded | shie | lded | unsh | elded | unshi | elded | |
| Recommended measuremen object geometry (flat) | nt | ø24 | mm | ø24 | mm | ø48 | mm | ø72 | mm | |
| Sensor cable length | | | | | 1 | m | | | | |
| Connection | | connector 5-pin M12 | | | | | | | | |
| Output | | 0.5 9.5V | | | | | | | | |
| Power supply | | 12V 32V | | | | | | | | |
| Protection class | | IP67 | | | | | | | | |
| Pressure resistance | | 10bar (sensor, cable and controller) | | | | | | | | |
| Weight | | 70 |)g | 75 | īg | 7 | 7g | 95 | ig | |
| FSO = of full scale output | | | | | | | | | | |

FSO = of full scale output MMR = midrange ¹⁾ Steel: ST37 DIN 1.0037 / aluminium: AlCuMgPb3.1645

²⁾ RMS noise relates to centre of measuring range at 5kHz



С

Installation instructions

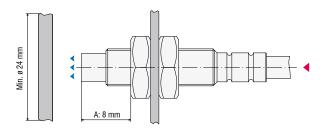
The relative size of the measurement object to the sensor and the position of the mounting nut have effects on the linearity deviation for eddy current sensors.

Please note:

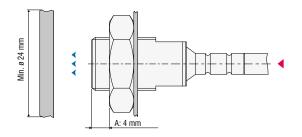
8

- Depending on the sensor model, the measurement object geometry shall be 2 or 4 times the sensor diameter.
- The mounting nut should not exceed the indicated dimension A.

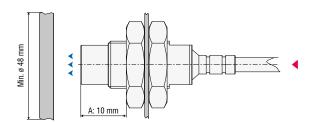
DT3005-U1-x-C1



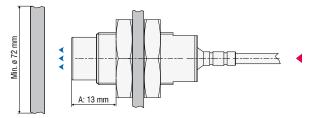
DT3005-S2-x-C1



DT3005-U3-x-C1



DT3005-U6-x-C1

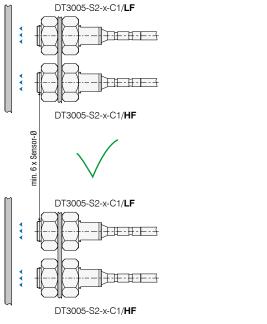


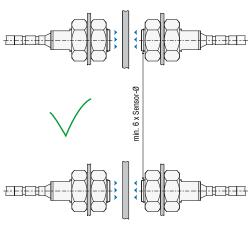
Multi-channel operation without mutual interference

If two or more systems operate next to one another, there is no need for synchronisation using a synchronisation cable. For operating several systems, a new frequency separation is provided (LF/HF), which enables to operate these systems in parallel without influencing one another.

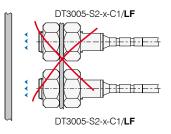
Please note:

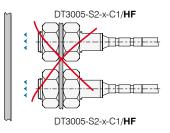
- The LF/HF sensor arrangement enables to mount two sensors next to one another.
- The distance between two pairs of sensors must be at least 6 times the sensor diameter.
- However, it is not possible to place 2 LF sensors or 2 HF sensors next to one another.





Correct LF/HF arrangement





Arrangement not possible

9

eddyNCDT 3010



- High accuracy and temperature stability
- Active temperature compensation
- Frequency response 25kHz (-3dB)
- For integration in harsh, industrial environments
- Multi-channel applications by synchronisation

System structure

The eddyNCDT 3010 is a compact, singlechannel system consisting of an eddy current sensor, a sensor connecting cable and an amplifier electronics (signal conditioning unit). The sensors are factory-calibrated for aluminium (non-ferromagnetic) or steel St37 (ferromagnetic). Using three-point linearisation, the user can also compensate on site for other materials.

Temperature compensation

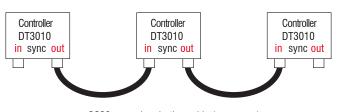
The eddyNCDT 3010 series is suitable in a wide temperature range. In the case of fluctuating ambient temperatures a stable output signal is very important for reliable measurements. Due to a patented temperature compensation method the eddyNCDT series 3010 offers a unique thermal stability, which no other system can offer.

The eddyNCDT 3010 is designed for industrial use in production plants, for machine control and for measuring and testing during in-process quality assurance.

Synchronisation

If several channels of series 3010 operate simultaneously close to one another, a mutual interference is possible because of slight differences in the oscillator frequencies.

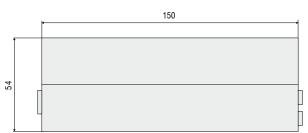
This can be avoided by synchronisation. Two SMC connectors at the electronic box, one for oscillator signal output (sync out) and one for input (sync in) are standard equipment. The electronics operate independently as long as they are not interconnected. If connected together, they automatically switch to synchronised operation and are controlled by the first electronics (master). Any quantity of units can be synchronised by serial connection.

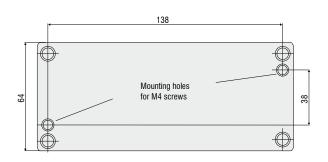


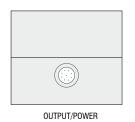
SC30 – synchronization cable (accessory)

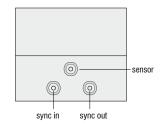
| Controller | ontroller | | DT3010-M | | |
|---|------------|---|----------------------|--|--|
| Material | Material | | ferromagnetic target | | |
| Linearity | | ≤±0.25% FSO | | | |
| Resolution 1) | | 0.0059 | % FSO | | |
| Repeatability | | 0.01% | 5 FSO | | |
| Frequency response | | 25kHz | (-3dB) | | |
| Temperature compensation range | | standard: 10 to 65°C optional 0 to 90°C | | | |
| T | | operation: 10 to 50°C | | | |
| Temperature range controller | | storage: -25 to 75°C | | | |
| Temperature stability controller (MMR) | | ≤0.05 % FSO/ °C | | | |
| Output | | 0 10V / 10mA and 4 20mA | | | |
| Power supply | | 24 VDC (9 30V) / 205mA | | | |
| Electromagnetic compatibility (EMC) | | acc. EN 50081-2 / EN 50082-2 | | | |
| Synchronisation | | with cable SC | 30 (accessory) | | |
| Protection class | controller | IP | 54 | | |
| FSO = of full scale output MMR = midrange ¹⁾ static resolution at midrange | | | | | |

Housing DT3010



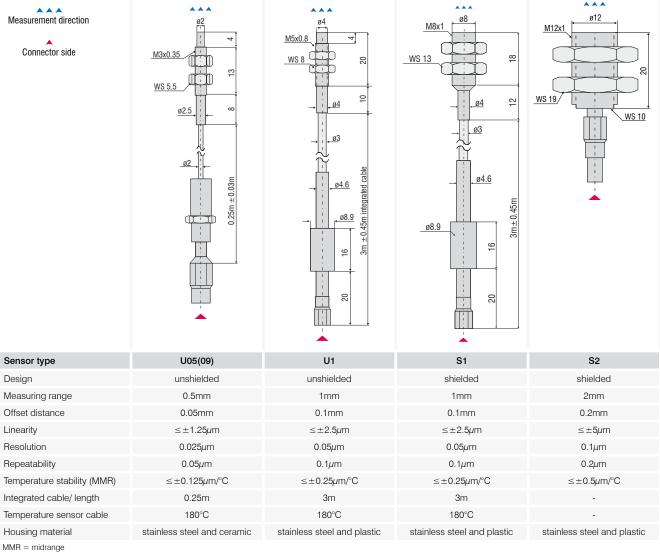


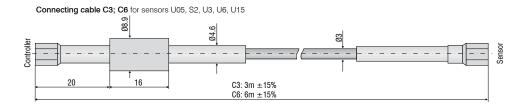


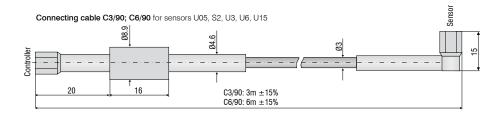


....

Measurement direction

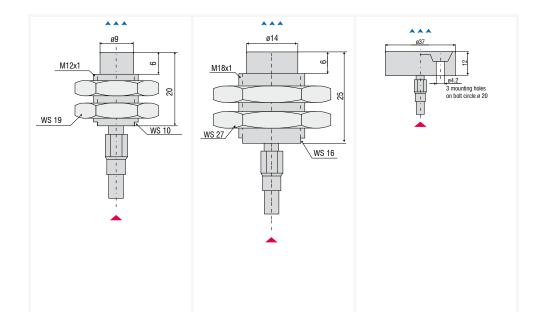






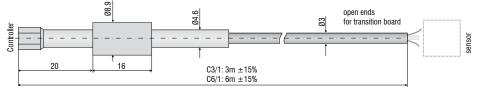
Measurement direction

Connector side



| Sensor type | U3 | U6 | U15 |
|-----------------------------|---------------------------------|---------------------------------|---------------------------|
| Design | unshielded | unshielded | unshielded |
| Measuring range | 3mm | 6mm | 15mm |
| Offset distance | 0.3mm | 0.6mm | 1.5mm |
| Linearity | $\leq \pm 7.5 \mu m$ | $\leq \pm 15 \mu m$ | \leq \pm 37.5 μ m |
| Resolution | 0.15µm | 0.3µm | 0.75µm |
| Repeatability | 0.3µm | 0.6µm | 1.5µm |
| Temperature stability (MMR) | $\leq \pm 0.75 \mu m/^{\circ}C$ | $\leq \pm 1.5 \mu m/^{\circ} C$ | \leq ±3.75 μ m/°C |
| Integrated cable/ length | - | - | - |
| Temperature sensor cable | - | - | - |
| Housing material | stainless steel and plastic | stainless steel and plastic | ероху |
| MMR = midrange | | | |

Connecting cable Cx/1



Cable Cx / Cx1 / Cx/90 Cable design Sheath material Temperature resistance Outer diameter Bending radius

Suitable for use with robots

Plug

 Plug

 Type

 Locking method

 Protection class

 Temperature resistance

 Material housing

 Mechanical service life

coaxial with sheath wire FEP/Flour-Thermoplast -50°C to +200°C 2.95mm ±0.05mm one-time bending during installation: 2 x cable diameter minimum bending radius for movement: 5 x cable diameter optimum bending radius at continuous movement: 10 x cable diameter no no

Sensor side/Controller side

female connector, coaxial, SMC screw no details -65 to +165°C brass nickel-plated > 500 mating cycles

Eddy current sensor system with simple web browser configuration



eddyNCDT 3100

- Easy sensor replacement
- Configuration via web browser
- High temperature stability, resolution and linearity
- Frequency response 25 kHz (-3dB)
- Multi channel applications: synchronisation of up to 10 controller

System design

The eddyNCDT 3100 includes an extremely compact controller and a displacement sensor. The sensors are connected through a 3m or 9m integrated, highly flexible cable and connected to the controller by a user-friendly push-pull plug-in connection.

The controller housing is made from solid cast aluminium and is protected to IP65. Alternative mounting options are slot nuts, mounting holes or a mounting rail. The robust sensors make the eddyNCDT 3100 system ideally suited to measurement tasks in the industrial environment.

Versatile in application

The eddyNCDT 3100 series is the new generation of eddy current displacement measurement systems. The measurement system uses a patented temperature compensation method to provide firstclass stability even with fluctuating temperatures. These sensors are an excellent choice when you need high precision in harsh industrial environments (pressure, dust, temperature).

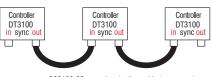
Sensors and cables come with an integrated memory module that stores all the major sensor and cable data. All sensors are factory calibrated to adjust to ferromagnetic and nonferromagnetic materials.

Multi-channel synchronisation

In the case that more sensors of the series eddyNCDT 3100 are operated next to each other, an influence due to a hardly different oscillator frequency (beat frequency) is possible. This can be avoided by synchronisation. The eddyNCDT 3100-SM is equipped with two additional connectors for the oscillator output ("SYNC OUT") and for the input ("SYNC IN). The electronics is working independently until a connection is built. By means of the connections with the synchronisation cable SC3100-0,3, the electronics switch automatically to synchronisation mode. In this way, two up to ten systems can be synchronised with each other.



All settings are made in the intuitive web interface, eliminating the need for any special software.

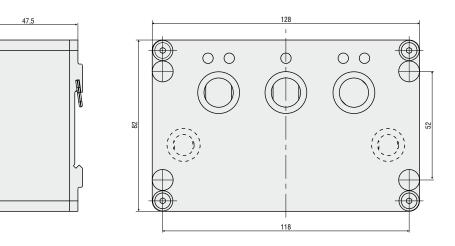


SC3100-03 - synchronisation cable (accessory)

| Controller | | DT3100 |
|--------------------------------|------------------|---|
| Linearity | | <± 0.25 % FSO |
| Resolution 1) | | 0.005 % FSO |
| - | | voltage output: 25kHz (-3dB) |
| Frequency response | | digital (Ethernet): 14.4kHz; 7.2kHz; 3.6kHz (each 16 bit) |
| Temperature compensation range | | standard: 10 65 °C |
| Temperature range | controller | operation: 10 50 °C |
| Temperature stability | controller (MMR) | 0.05 % FSO / °C |
| Outputs | | 0 10 V / - 5 + 5 V / 4 20 mA / Ethernet |
| Power supply | | 24 VDC (11 30V) / ca. 5W |
| Synchronisation | only DT3100-SM | via cable SC 3100-0,3 (accessories) |
| Protection class | controller | IP65 (connected plug-in connections/covers) |

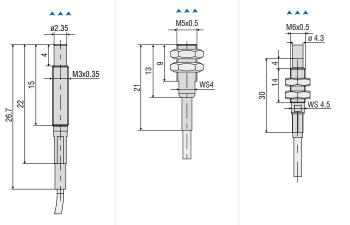
FSO = of full scale output MMR = midrange ¹⁾ Static resolution, relates to centre of measuring range; effective value (RMS)

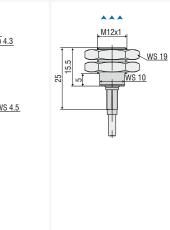
Controller housing DT3100 / DT3100-SM



15

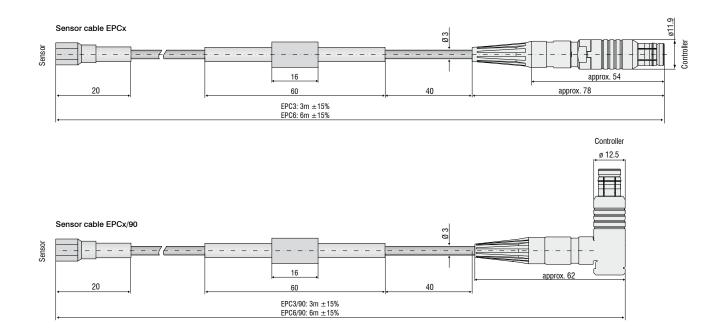
Measurement direction



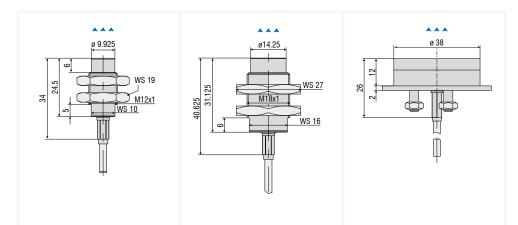


| Sensor type | EPU05 | EPS08 | EPU1 | EPS2 |
|-----------------------------------|---------------------------------|----------------------------------|--------------------------------|-------------------------------|
| Design | unshielded | shielded | unshielded | shielded |
| Measuring range | 0.5mm | 0.8mm | 1mm | 2mm |
| Offset distance | 0.05mm | 0.08mm | 0.1mm | 0.2mm |
| Linearity | $\leq \pm 1.25 \mu m$ | ≤±2µm | $\leq \pm 2.5 \mu m$ | $\leq \pm 5 \mu m$ |
| Resolution | 0.025µm | 0.04µm | 0.05µm | 0.1 <i>µ</i> m |
| Temperature stability (MMR) | $\leq \pm 0.25 \mu m/^{\circ}C$ | $\leq \pm 0.4 \ \mu m/^{\circ}C$ | $\leq \pm 0.5 \mu m/^{\circ}C$ | $\leq \pm 1 \mu m/^{\circ} C$ |
| Temperature max. | 100°C | 100°C | 100°C | 100°C |
| Protection class (front and rear) | IP67 | IP67 | IP67 | IP67 |
| Integrated cable/ length | 3m | 3m | 3m/9m | 3m/9m |
| Temperature sensor cable | 100°C | 100°C | 100°C | 100°C |
| Housing material | stainless steel and ceramic | stainless steel and plastic | stainless steel and plastic | stainless steel and plastic |

MMR = midrange

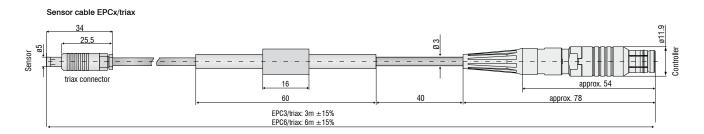


Measurement direction



| Sensor type | EPU3 | EPU6 | EPU15 |
|-----------------------------------|--------------------------------|-----------------------------|---------------------------------|
| Design | unshielded | unshielded | unshielded |
| Measuring range | 3mm | 6mm | 15mm |
| Offset distance | 0.3mm | 0.6mm | 1.5mm |
| Linearity | $\leq \pm 7.5 \mu m$ | $\leq \pm 15 \mu m$ | ≤±37.5µm |
| Resolution | 0.1 <i>5µ</i> m | 0.3µm | 0.75µm |
| Temperature stability (MMR) | $\leq \pm 1.5 \mu m/^{\circ}C$ | $\leq \pm 3\mu$ m/°C | $\leq \pm 7.5 \mu m/^{\circ} C$ |
| Temperature max. | 100°C | 100°C | 100°C |
| Protection class (front and rear) | IP67 | IP67 | IP67 |
| Integrated cable/ length | 3m/9m | 3m/9m | 3m/9m |
| Temperature sensor cable | 100°C | 100°C | 100°C |
| Housing material | stainless steel and plastic | stainless steel and plastic | ероху |

MMR = midrange



Plug Model

Cable Cable design Sheath material Temperature resistance Outer diameter Length tolerance Bending radius

Suitable for use with robots

Type Locking method Protection class Temperature resistance Material housing Mechanical service life

coaxial TPE-U/ thermoplastic elastomers -40°C to +90°C 2.90mm ±0.2mm ±15% one-time bending during installation: 7.5 x cable diameter minimum bending radius for movement: 15 x cable diameter no

Controller side

6-pole male connector push-pull IP68 (when connected) -40 to +120°C Copper, nickel-plated > 500 mating cycles

Sensor side EPCx / EPCx/90

female connector, coaxial, SMC screw no details -65 to +165°C Brass, gold plated > 500 mating cycles

EPCx/triax

male connector, triaxial push-pull IP67 (when connected) -30 to +150°C Brass nickel-plated, mat > 500 mating cycles 17

18 High precision eddy current displacement measurement

eddyNCDT 3300



- Micrometer accuracy
- Ideal for fast measurements: Frequency response up to 100kHz (-3dB)
- Numerous sensor models even for customer-specific applications
- Robust sensor construction for harsh environments
- Synchronised multi-channel measurement

The eddyNCDT 3300 eddy current measuring system is one of the most flexible and highest performing eddy current displacement measurement systems worldwide. Due to a mature technical design, the system offers numerous benefits to customers in multiple application areas such as manufacturing automation, machine monitoring and quality control.

Multifunctional controller

The eddyNCDT 3300 system includes high-performance processors for reliable signal conditioning and further processing. The innovative three-point linearisation technique it uses enables almost completely automatic linearisation which makes possible the optimum accuracies for every metallic measuring object and every installation environment. Operation is supported by an illuminated LC graphical display and on-screen prompts.

Linearisation and calibration

Systems in the eddyNCDT 3300 series can be individually linearised and calibrated by the user. Therefore, optimum measurement accuracies will always be achieved, even in the case of failed measuring object materials or harsh ambient conditions. The adjustment is made using three distance points $(\mathbb{O},\mathbb{Q},\mathbb{G})$ which are defined by a reference standard.

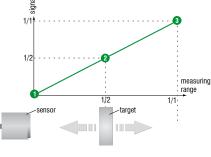
Maximum precision due to field calibration

In order to achieve maximum precision, eddyNCDT 3300 provides the field calibration function for achieving extremely precise measurement results. The following influences are taken into account:

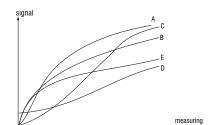
- A: Different target materials
- B: Different target sizes (measuring spot)
- C: Target shape
- D: Side preattenuation

E: Target tilt angle

The measuring range can also be extended using the field calibration.







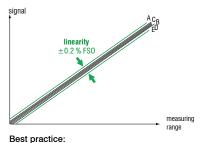
Conventional sensor without field calibration Massive linearity deviation results from the different influences

range



Synchronisation for multi-channel applications

The MCT304 multi-channel platform is available for thickness and displacement measurements with up to four channels. Up to four controllers can be integrated in a single MCT platform. The platforms can be synchronised with each other, whereby the simultaneous operation of any number of eddyNCDT sensors is possible. In order to compensate for opposing sensor influences, there are synchronisation inputs and outputs.



eddyNCDT 3300 with Micro-Epsilon field calibration High accuracy though compensation of the influences

| Controller | | DT3300 | DT3301 | | | |
|---|---|--|--|--|--|--|
| Linearity | | ≤±0.2 % FSO | | | | |
| | up to 25Hz | ≤0.005 % FSO (≤0.01 % FSO | ≤0.005 % FSO (≤0.01 % FSO using ES04, ES05 and EU05) | | | |
| Resolution ²⁾ | up to 2.5kHz | ≤0.01 % FSO | | | | |
| | up to 25 / 100kHz ≤0.2 % FSO | | | | | |
| Frequency response | sponse selectable 25kHz / 2.5kHz / 25Hz (-3 dB); 100kHz for measuring ranges ≤1mm | | | | | |
| Temperature compensat | tion | 10 100°C (option TCS: -40 180°C) 3) | | | | |
| Temperature range | controller | 5 5 | 50°C | | | |
| Outputs | | selectable 0 5V / 0 10V / \pm 2.5V / \pm 5V / \pm | 10V (or inverted) / 4 20mA (load 350 ohm) | | | |
| Power supply | | $\pm 12 VDC$ / 100mA, 5.2VDC / 220mA $^{1)}$ | 11 - 32VDC / 700mA | | | |
| Synchronisation | | via cable PSC 30 (accessories) via cable E SC 30 (accessories) | | | | |
| Electromagnetic compa | tibility | acc. to EN 50081-2 / EN 61000-6-2 | | | | |
| Controller functions limit switches, auto-zero, peak-to-peak, minimum, maximum, average, storage of 3 configurations (calibrations) | | | | | | |

FSO = Full Scale Output

Reference material: Aluminum (non-ferromagnetic) and Mild Steel DIN 1.0037 (ferromagnetic)

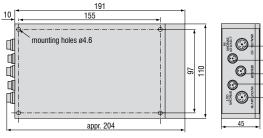
Reference temperature for reported data is 20°C (70°F); Resolution and temperature stability refer to midrange

Data may differ with magnetic inhomogeneous material.

¹⁾ additional 24VDC for external reset and limit switch ²⁾ resolution data are based on noise peak-to-peak values

³⁾ temperature stability may differ with option TCS

Controller dimensions



Output analog (U+I) Input power / sync. Sensor Output power / sync. Switches input/output 24 VDC In



Quadruple limit switch

- Two freely definable minimum and maximum limit values
- Individual switching threshold
- LED display for upper and lower limit warnings

Automatic calibration

 Three-point linearisation for optimum onsite calibration

Four configurations can be stored

- Factory calibration and three individual configurations can be stored
- Simple microprocessor-controlled singlecycle calibration





Types of output

- Voltage / current
- Metric / inch and graphical display
- Display of auto-zero, peak-to-peak value, minimum, maximum
- Scalable display for conversion to indirect measured values

180°C

stainless steel and plastic

Measurement direction ø2 M5x0.5 M4x0.35 M3x0,35 Connector side 13.75 0.3x45° 13 ± 0.1 M3 5 5 ٢ WS4 WS 3.2 ø2 ø2.5 ø2 Cable length 0.25 m ± 0.04 m Cable length 0.25 m Cable length 0.25 m ± 0.04 m 1:1 1:1 1:1 Sensor type ES04 EU05 ES08 Design shielded unshielded shielded Measuring range 0.4mm 0.4mm 0.8mm Offset distance 0.04mm 0.05mm 0.08mm Linearity $\leq \pm 0.8 \mu m$ $\leq \pm 1 \mu m$ $\leq \pm 1.6 \mu m$ Resolution 0.02µm 0.025µm 0.04µm Temperature stability (MMR) ≤±0.06µm/°C ≤±0.075µm/°C ≤±0.12µm/°C Temperature max. 150°C 150°C 150°C Pressure resistance sensor front 100bar 20bar Integrated cable/ length approx. 0.25m approx. 0.25m approx. 0.25m

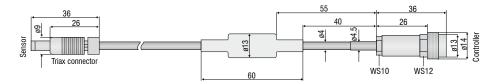
180°C

stainless steel and ceramic

Housing material MMR = midrange

Temperature sensor cable

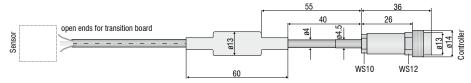
ECx sensor cable, length is selectable up to $x \le 15m$

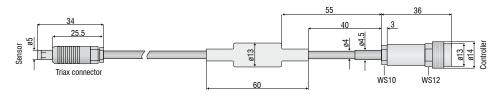


180°C

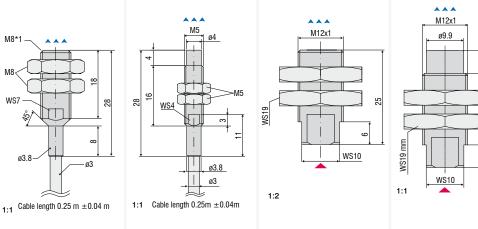
stainless steel







Measurement direction Connector side



| Sensor type | ES1 | EU1 | ES2 | EU3 |
|----------------------------------|-----------------------------|---------------------------------|--------------------------------|------------------------------|
| Design | shielded | unshielded | shielded | unshielded |
| Measuring range | 1mm | 1mm | 2mm | 3mm |
| Offset distance | 0.1mm | 0.1mm | 0.2mm | 0.3mm |
| Linearity | $\leq \pm 2\mu m$ | ≤±2µm | $\leq \pm 4 \mu m$ | $\leq \pm 6 \mu m$ |
| Resolution | 0.05µm | 0.05µm | 0.1µm | 0.15µm |
| Temperature stability (MMR) | $\leq \pm 0.15 \mu$ m/°C | $\leq \pm 0.15 \mu m/^{\circ}C$ | $\leq \pm 0.3 \mu m/^{\circ}C$ | \leq \pm 0.45 μ m/°C |
| Temperature max. | 150°C | 150°C | 150°C | 150°C |
| Pressure resistance sensor front | - | - | 20 bar | 20 bar |
| Integrated cable/ length | approx. 0.25m | approx. 0.25m | - | - |
| Temperature sensor cable | 180 °C | 180 °C | - | - |
| Housing material | stainless steel and plastic | stainless steel and plastic | stainless steel and plastic | stainless steel and plastic |
| MMD with a set | | | | |

MMR = midrange

Cable

Cable design Sheath material Temperature resistance Outer diameter Bending radius

Suitable for use with robots

Controller side

cable socket

-30 to +85°C

screw

IP67

Plug

Model Туре

Locking method Protection class Temperature resistance Material housing Mechanical service life

coaxial with sheath wire FEP/Flour-Thermoplast -30°C to +200°C 3.9mm ±0.1mm one-time bending during installation: 2 x cable diameter minimum bending radius for movement: 5 x cable diameter optimum bending radius at continuous movement: 10 x cable diameter no

Sensor side ECx 5-pole female connector, male connector, triaxial push-pull IP67 (when connected) -30 to +150°C Brass nickel-plated Brass nickel-plated, mat > 500 mating cycles > 500 mating cycles

ECx/1 male connector 5-pol screw IP67 (when connected) -40 to +85°C Brass nickel-plated > 500 mating cycles

ECx/2 male connector, triaxial

push-pull IP68 -65 to +135°C Brass nickel-plated, mat > 500 mating cycles

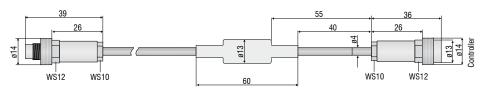
9

9

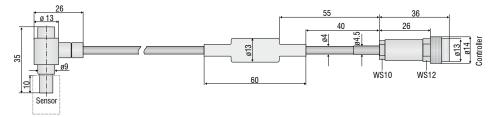
33

| Measurement direction Connector side | Image: select | 1:2 | 1:2 |
|---|---|---------------------------------|--------------------------------|
| Sensor type | ES4 | EU6 | EU8 |
| Design | shielded | unshielded | unshielded |
| Measuring range | 4mm | 6mm | 8mm |
| Offset distance | 0.4mm | 0.6mm | 0.8mm |
| Linearity | $\leq \pm 8 \mu m$ | ≤±12µm | ≤±16µm |
| Resolution | 0.2µm | 0.3µm | 0.4µm |
| Temperature stability (MMR) | $\leq \pm 0.6 \mu m/^{\circ} C$ | $\leq \pm 0.9 \mu m/^{\circ} C$ | $\leq \pm 1.2 \mu m/^{\circ}C$ |
| Temperature max. | 150°C | 150°C | 150°C |
| Pressure resistance sensor front | 20bar | 20bar | 20bar |
| Integrated cable/ length | - | - | - |
| Temperature sensor cable | - | - | - |
| Housing material | stainless steel and plastic | stainless steel and plastic | stainless steel and plastic |
| MMD midronge | | | |

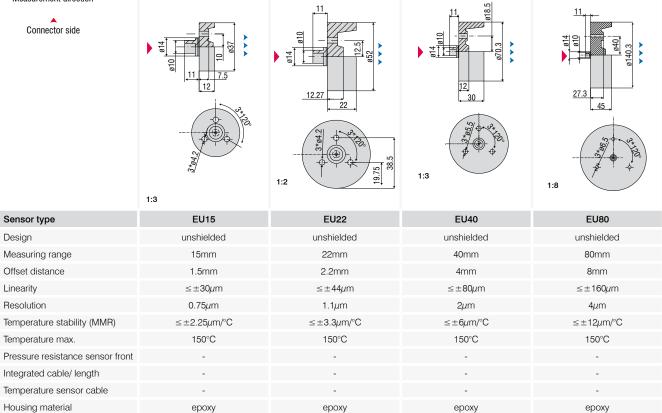
MMR = midrange



ECx/90 sensor cable with 90° connector (sensor-sided), length is selectable up to x \leq 15 m







MMR = midrange

Cable

Cable design Sheath material Temperature resistance Outer diameter Bending radius

Suitable for use with robots

Plug Model Туре

Locking method Protection class Temperature resistance Material housing Mechanical service life

coaxial with sheath wire FEP/Flour-Thermoplast -30°C to +200°C 3.9mm ± 0.1mm one-time bending during installation: 2 x cable diameter minimum bending radius for movement: 5 x cable diameter optimum bending radius at continuous movement: 10 x cable diameter no

Controller side

5-pole female connector, cable socket screw IP67 -30 to +85°C Brass nickel-plated > 500 mating cycles

Sensor side ECEx 5-pole male connector screw IP67 (when connected) -30 to +85°C Brass nickel-plated > 500 mating cycles

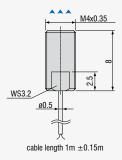
ECx/90 male connector, triaxial, angle push-pull IP67 (when connected) -65 to +135°C Brass nickel-plated, mat > 500 mating cycles

24

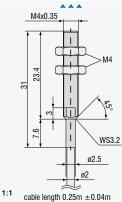


Subminiature sensors for confined installation space

In addition to standard sensors in conventional designs, miniature sensors can also be supplied which achieve high precision measurement results with the smallest possible dimensions. Pressure-resistant versions, screened housings, ceramic types and other special features characterise these sensors, which achieve highly accurate measurement results despite the small dimensions. The miniature sensors are employed in high pressure applications, e.g. in combustion engines.







ES04(34) Shielded Sensor

ES04/180(25) Shielded Sensor

Temperature stability $\leq \pm 0.025\%$ FSO/°C

Connection: integrated coaxial cable

Max. operating temperature: 180°C

Housing material: stainless steel

Sensor cable: ECx/1 or ECx/2,

1m (ø 0.5mm), short silicon tube

Pressure resistance (static):

Measuring range 0.4mm

at cable exit

front 100bar

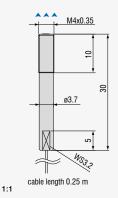
length ≤6m

Measuring range 0.4mm Temperature stability ≤±0.025%FSO/°C Connection: integrated coaxial cable 0.25m (Ø 2mm) with sealed triaxial connector Pressure resistance (static):

front 100bar / rear side splash water Max. operating temperature: 150°C

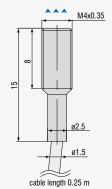
Housing material: stainless steel and ceramic

Sensor cable: ECx, length $\leq 6m$



ES04/180(27) Shielded Sensor

Measuring range 0.4mm Temperature stability $\leq \pm 0.025\%$ FSO/°C Connection: integrated coaxial cable 0.25m (Ø 0.5mm) with solder connection board Pressure resistance (static): front 100bar Max. operating temperature: 180°C Housing material: stainless steel Sensor cable: ECx/1, length $\leq 6m$

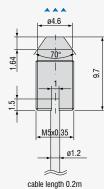


2:1

3:1

ES04(35) Shielded Sensor

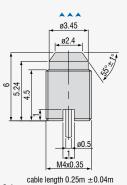
Measuring range 0.4mm Temperature stability $\leq \pm 0.025\%$ FSO/°C Connection: integrated coaxial cable 0.25m (Ø 1.5mm) with sealed triaxial connector Pressure resistance (static): front 100bar / rear side 5 bar Max. operating temperature: 150°C Housing material: stainless steel and ceramic Sensor cable: ECx/1, length $\leq 6m$



2:1

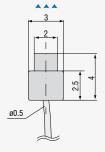
ES04(44) Shielded Sensor

Measuring range 0.4mm Temperature stability $\leq \pm 0.025\%$ FSO/°C Connection: integrated coaxial cable 0.2m (ø 1.2mm) with sealed triaxial connector Pressure resistance (static): front 100bar / rear side splash water Max. operating temperature: 150°C Housing material: stainless steel and ceramic Sensor cable: ECx, length $\leq 6m$



ES04(70) Shielded Sensor

Measuring range 0.4mm Temperature stability $\leq \pm 0.025\%$ FSO/°C Connection: integrated coaxial cable 0.25m (0 0.5mm) with solder connection board Pressure resistance (static): front 100bar / rear side splash water Max. operating temperature: 150°C Housing material: stainless steel and ceramic Sensor cable: ECx/1, length ≤ 6 m

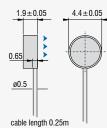


cable length 0.25m ± 0.04 m

3:1

EU05(10) Unshielded Sensor Measuring range 0.5mm Temperature stability $\leq \pm 0.025\%$ FSO/°C Connection: integrated coaxial cable 0.25m (a 0.5mm) with solder connection board Max. operating temperature: 150°C

Housing material: stainless steel and ceramic Sensor cable: ECx/1, length $\leq 6m$



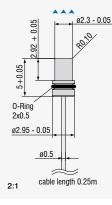
ES05/180(16) Shielded Sensor

Measuring range 0.5mm Temperature stability $\leq \pm 0.025\%$ FSO/°C Connection: integrated coaxial cable 0.25m (Ø 0.5mm) with solder connection board Max. operating temperature: 180°C Housing material: stainless steel and epoxy Sensor cable: ECx/1, length $\leq 6m$

3:1

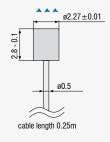
totale length 0.5m 0.

ES05(36) Shielded Sensor Measuring range 0.5mm Connection: integrated coaxial cable 0.5m (ø 0.5mm) with solder connection board Max. operating temperature: 150°C Housing material: stainless steel and epoxy Sensor cable: ECx/1, length ≤6m



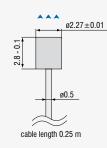
EU05(65) Unshielded Sensor Measuring range 0.5mm

Connection: integrated coaxial cable 0.25m (Ø 0.5mm) with solder connection board Pressure resistance (static): front 700bar / rear side splash water Max. operating temperature: 150°C Housing material: ceramic Sensor cable: ECx/1, length ≤6m



EU05(66) Unshielded Sensor

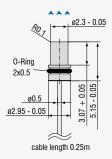
Measuring range 0.5mm Temperature stability $\leq \pm 0.025\%$ FSO/°C Connection: integrated coaxial cable 0.25m (Ø 0.5mm) with solder connection board Pressure resistance (static): front 400bar / rear side splash water Max. operating temperature: 150°C Housing material: ceramic Sensor cable: ECx/1, length $\leq 6m$



EU05(72) Unshielded Sensor

Measuring range 0.4mm Temperature stability $\leq \pm 0.025\%$ FSO/°C Connection: integrated coaxial cable 0.25m (Ø 0.5mm) with solder connection board Pressure resistance (static): front 2000bar / rear side splash water Max. operating temperature: 150°C Housing material: ceramic Sensor cable: ECx/1, length $\leq 6m$

3:1



EU05(93) Unshielded Sensor

Measuring range 0.4mm Temperature stability $\leq \pm 0.025\%$ FSO/°C Connection: integrated coaxial cable 0.25m (Ø 0.5mm) with solder connection board Pressure resistance (static): front 2000bar / rear side splash water Max. operating temperature: 150°C Housing material: ceramic Sensor cable: ECx/1, length $\leq 6m$ 3:1

turboSPEED DZ140



- Maximum speed range from 200 to 400,000 RPM
- Miniature sensor design from ø3mm
- Measurement on aluminium and titanium
- Distance to target up to 2.2mm
- No modification of the compressor wheel
- For test cell and on-vehicle measurements
- Highest EMV immunity and stability
- Operating temperature up to 285°C

Measuring principle

A coil is integrated in a sensor housing and energised by a highfrequency alternating current. The electromagnetic field from the coil generates eddy currents in the turbocharger blade, while every blade generates a pulse. The controller identifies the speed (analogue 0–5V) by considering the number of blades.

Robust miniature controller

As the entire electronics is in a sealed miniature housing and designed for ambient temperatures up to 115°C, the controller is easy to integrate into the engine compartment. turboSPEED DZ140 offers excellent EMV immunity in test cells and road tests.

Reliable speed and temperature measurement

The DZ140 eddy current measuring system is resistant to oil and dirt, which is a key advantage compared to optical speed measuring systems, as this helps to achieve high precision measurements on a continuous basis. The integrated temperature measurement feature records as well the actual ambient temperature near to the sensor.

Ease of use

A tri-colour 'status' LED on the controller indicates when the sensor has reached the ideal distance from the turbocharger blades. This simple feature enables greatly reduced installation time. As the sensor is connected with the electronics via a special BNC connector, it is therefore downward compatible with all previous sensor models. An industrial push-pull connector guarantees a reliable connection between the electronics and the power supply as well as the analogue outputs.

Measurement of aluminium and titanium blades

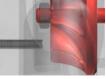
The DZ140 measures both aluminium and titanium blades. The sensors can be mounted at a relatively large distance from the blade. The maximum distance of 2.2mm enables reliable operation.



Extremely compact design



Large measuring distances both at aluminium and titanium



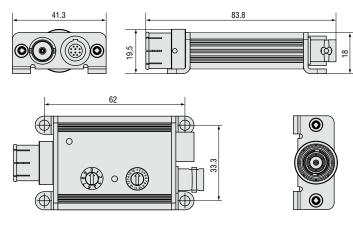
axial installation

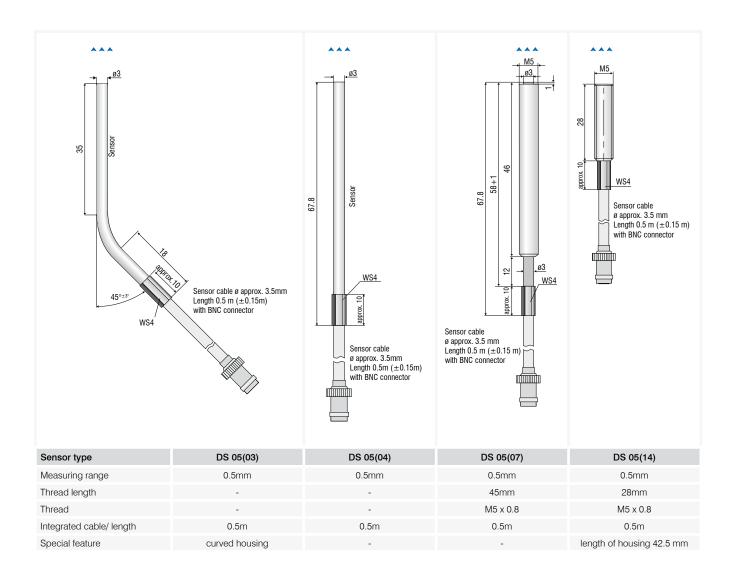


radial installation

| Model | | DZ140 (Controller) | | | | | | | |
|--|---|--|-----------|-----------|----------------------------|-----------|------|----------|--------|
| Sensors | | DS 05(03) | DS 05(04) | DS 05(07) | DS 05(14) | DS 05(15) | DS 1 | DS 1(04) | DS 1/T |
| Measuring principle | | eddy current principle | | | | | | | |
| Target (blade material) | | aluminium or titanium | | | | | | | |
| Maximum speed range (measuring range) | | 200 400,000RPM | | | | | | | |
| Operating controlle | | -20 +115°C | | | | | | | |
| temperature | sensor | -40 +235°C (short-term +285°C) | | | | | | | |
| Distance sensor to blade (wall thickness 0.35mm) | aluminium | radial 0.6mm / axial 1.1mm | | | radial 1.3mm / axial 2.2mm | | | | |
| | titan | radial 0.6mm / axial 1.0mm | | | radial 1.2mm / axial 2.1mm | | | | |
| | | adjustment with three-state LED | | | | | | | |
| Integral sensor cable | | 0.5m 0.75m 0.8r ±0.15m ±0.15m ±0.1 | | | | | | | |
| Number of blades | | rotary switch (accessible from the outside) for 1 up to 16 blades | | | | | | | |
| Output (digital) | | 1 pulse / blade (TTL-level, variable pulse duration) or 1 pulse / revolution (TTL-level, pulse duration 100 μ s) | | | | | | | |
| | | 0 5V (200 200,000RPM) 0 5V (200 400,000RPM) adjustable, from the outside accessible via mode rotary switch | | | | | | | |
| Output (analogue) | linearity | ±0.2% FSO | | | | | | | |
| | resolution | 0.1% FSO | | | | | | | |
| | | test pulse generation to control the measurement chain; load resistance >5kOhm, load capacitance max. 1nF | | | | | | | |
| Output sensor temperature | | 0 5V (-50 +300°C) | | | | | | | |
| RAW output (via BNC connector) | for easy sensor mounting via oscilloscope | | | | | | | | |
| Power supply | | 9V 30VDC / max. 50mA (short-term up to 36VDC) | | | | | | | |
| Cable | | PC140-3 supply and output cable 3m | | | | | | | |
| Cable | | PC140-6 supply and output cable 6m | | | | | | | |
| Weight | | controller DZ140: appr. 85g | | | | | | | |
| Protection class | controller DZ140: IP 65 | | | | | | | | |
| FSO = Full Scale Output | | | | | | | | | |

Controller DZ140





Mounting adapter MA135



For sensors DS05(03) and DS05(04)included.

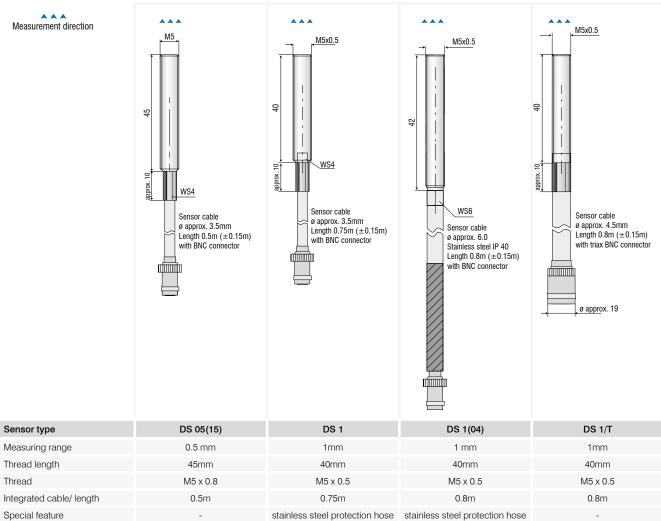


Sensor type

Thread length

Special feature

Thread



eddyNCDT SGS4701



- Miniature sensor design
- Sensor technology can be integrated completely into the sensor
- Miniature, compact controller can be integrated in the spindle or installed on the housing via a flange
- Suitable for ferro- and non-ferromagnetic materials
- Temperature measurement integrated in the sensor
- Cost-effective design

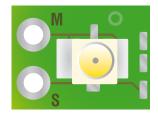
Measuring thermal expansion in spindles

The displacement measurement system SGS 4701 (Spindle Growth System) has been developed specifically for high speed milling machine applications. Due to high machining speeds and the heat generated, the linear thermal expansion of the precision machine tool spindle needs to be compensated for in order to keep the tool in a defined position at all times. The SGS sensor measures the thermal and centrifugal force expansion of the spindle. These measurement values are fed into the CNC machine tool as correction values, compensating for any positioning errors.

The SGS 4701 operates on the eddy current measuring principle. This non-contact measurement is wear-free. Furthermore, the measurement procedure is resistant to disturbances such as heat, dust and oil.

System structure

The SGS 4701 consists of a sensor, a sensor cable and a controller, factory calibrated for ferromagnetic and non-ferromagnetic measurement objects. Two miniature sensors enable it to be installed directly in the spindle, where the measurements take place, typically on the labyrinth-ring of the spindle. As well as measuring linear thermal expansion, the temperature of the sensor is also detected and output. The compact controller can be installed on the spindle housing via a flange or directly in the spindle.



The sensor cable must not be shortened as functionality loss may arise. Removing the connector is only permitted behind the plug-sided crimp when using the solder connections.

 $\mathbf{S} = \text{Signal} = \text{inner conductor}$ $\mathbf{M} = \text{ground} = \text{shield} = \text{outer conductor}$

8-pin. M12 connector

(6) (4) (7) (8) (3) (1) (2)

| Pin | Signal |
|-----|---------------------|
| 1 | Ground |
| 2 | +24V |
| 3 | Displacement signal |
| 4 | Temperature signal |
| 5 | not connected |
| 6 | do not connect |
| 7 | do not connect |
| 8 | not connected |

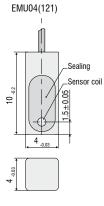
Pin assignment (view on controller)

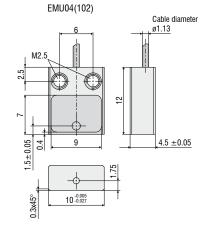
| Sensor system | | SGS4701 | | | |
|--------------------------------|---------------------|--|--|--|--|
| Measuring range | | 500µm (option 250µm ²) | | | |
| Offset | | 100µm (option 50µm 2) | | | |
| Linearity | | $\pm 2\mu m$ | | | |
| Resolution ¹⁾ | | 0.5µm | | | |
| Frequency response | | 2000Hz | | | |
| Target | | ferromagnetic / non-ferromagnetic | | | |
| Minimum target diameter | | 6 mm (option 3.5 mm ²⁾) | | | |
| Operating temperature | sensor | 0 +90°C | | | |
| | controller | 10 +70°C | | | |
| To any state of the life of | sensor | ±150ppm FSO/°C (MMR) | | | |
| Temperature stability | controller | ±500ppm FSO/°C (MMR) | | | |
| - | sensor | +10 +80°C | | | |
| Temperature compensation range | controller | +10 +70°C | | | |
| Supply voltage | | 12 32VDC | | | |
| A 1 1 | displacement | $0,5 - 9,5V \triangleq 100 - 600 \mu m$ (option 50 - $300 \mu m^{2}$) | | | |
| Analog out | temperature | 0.5 - 9.5V (≙ 0 +90°C) | | | |
| Protection class | sensor / controller | IP67 | | | |
| Dimensiona | EMU04(102) | 12x10x4.5mm ³ | | | |
| Dimensions | EMU04(121) | 10x4x4mm ³ | | | |
| Sensor cable ³⁾ | diameter | Ø 1.13mm | | | |
| | length | 1000 mm (400 - 1500 mm on request) | | | |
| | min. bending radius | 12mm | | | |
| | jacket | FEP | | | |
| | | | | | |

FSO = Full Scale Output; MMR = Midrange

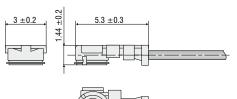
¹⁾ static, MMR

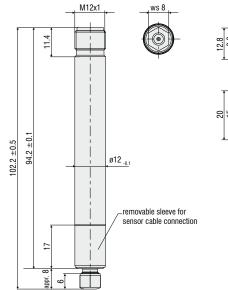
²⁾ For OEM modifications: sensor with measuring range 250µm and offset 50µm ³⁾ Detailled cable specifications can be found in the operating manual





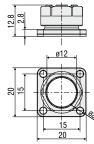
Connector (max. 20 mating cycles possible)





Controller

Mounting flange (optional)



32

eddyNCDT

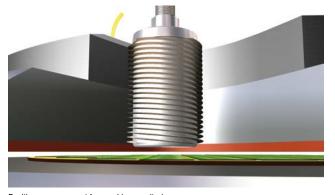
Eddy current sensors from Micro-Epsilon have many possible areas of application. High measurement accuracy and frequency response together with an extremely robust design enable measurements where conventional sensors are not applicable.

Eddy current sensors from Micro-Epsilon represent high-performance measurement, particularly under extreme operating conditions. Environmental influences such as oil, temperature, pressure and moisture are largely compensated for and have a minimal effect on the signal. For this reason, the sensors are ideal in challenging application areas, such as industrial mechanical engineering and automotive inspection systems.





Measuring the axial shaft oscillation



Position measurement for machine monitoring



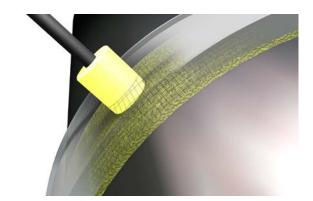
Measuring the thermal expansion



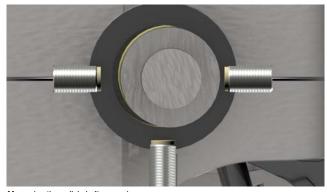
Monitoring the lubricating gap in the combustion engine



Run-out monitoring of rollers



Measurement of oil film thickness



Measuring the radial shaft expansion

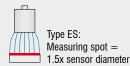
Accessories

| Articel | Description | eddyNCDT 3001 | eddyNCDT 3005 | eddyNCDT 3010 | eddyNCDT 3100 | eddyNCDT 3300 |
|----------------|---|------------------|------------------|------------------|------------------|------------------|
| PC3/8 | Power- and output cable, 3m, 8 pin | | | • | | |
| PC5/5 | Power- and signal cable | • | • | | | |
| SC30 | Synchronisation cable, 30cm | | | • | | |
| CSP 301 | Digital signal processing and display unit up to 2 channels | | | • | | |
| PC3100-3/6/BNC | Outputcable and supply unit, 3m | | | | • | |
| PS2020 | Power Supply 24V / 2.5A; Input 100-240 VAC; Output 24 VDC / 2.5A; DIN rail mounting; 35mm x 7.5mm, DIN 50022 | | | | • | • |
| MC2.5 | Micrometer calibration fixture, range 0 to 2.5 mm, division 1 μm , for sensors EPU05 to EPS2, adjustable offset (zero) | | | • | • | • |
| MC25D | Micrometer calibration fixture, range 0 to 25mm, division 1 μm , for sensors EPU05 to EPU15, adjustable offset (zero) | | | • | • | • |
| ECx | Sensor cable, length selectable up to 15m | | | | | • |
| ECx/90 | Sensor cable with 90° connector (sensor-sided) length selectable up to 15m | | | | | • |
| ECx/1 | Extension cable for solder connection | | | | | • |
| ECx/2 | Extension cable for plug connection | | | | | • |
| SCA3/5 | Signal cable analogue, 3m | | | | | • |
| SCA3/5/BNC | Signal cable analogue with BNC connector, 3m | | | | | • |
| SCD3/8 | Signal cable digital (switch input/outout), 3m (also for supply 11 - 32VDC); for DT3301 | | | | | • |
| SIC3(07) | Signal cable with BNC connector for direct operation with oscilloscope | | | | | • |
| PSC30 | Power / Synchronisation cable, 0.3m, for DT3300 | | | | | • |
| ESC30 | Synchronisation cable, 0.3m, for DT3301 | | | | | • |
| PS300/12/5 | Power supply Input 100 - 240VAC; Output \pm 12VDC / 5.2VDC integrated cable 1.5m; for max. 4x DT3300 | | | | | • |
| MBC300 | Mounting base for controller DT330x, fixing through M4 threaded holes 166x108x60mm | | | | | • |
| MCT304-SM | Tower for max. 4 controller DT 3300; supply 100 - 240VAC | | | | | • |
| MCT304(01) | Tower for max. 4 controller DT 3301; supply 11 - 32VDC | | | | | • |
| | | | | | | |

34

eddyNCDT

Target size of eddy current sensors



ES (shielded sensor) Measuring spot = 1.5x sensor diameter

Type EU: Measuring spot = 3x sensor diameter

EU (unshielded sensor) Measuring spot = 3x sensor diameter

The relative size of the measuring object to the sensor affects the linearity deviation for eddy current sensors. Ideally, the measuring object size for shielded sensors should be at least 1.5 times the diameter of the sensor and at least three times the diameter of the sensor for unshielded ones. From this size, almost all lines of the magnetic field run from the sensor to the target. Therefore, almost all magnetic field lines penetrate the target via the face and so contribute to eddy current generation, where only a small linearity deviation occurs.

Factory calibration

- As standard, the eddy current sensors are tuned to
- St37 for ferromagnetic calibration.
- Aluminium for non-ferromagnetic calibration
- With other materials a factory calibration is recommended.

Choosing the right sensor

Eddy current sensors are grouped into shielded (e.g. ES05) and unshielded (e.g. EU05) sensors. With shielded sensors, the field lines run closer together due to a separate casing. These are less sensitive to radial flanking metals. With unshielded sensors, the field lines emerge at the side of the sensor normally causing an extended measuring range. Correct installation is important for signal quality. The following information applies for mounting in ferromagnetic and non-ferromagnetic materials.

Assembly references for shielded sensors (ES) in metal

✓ Correct

Flush mounting



Protruding mounting

🗶 False

Surrounding material attenuates the sensor; Measurement not possible.

Assembly references for unshielded sensors (EU) in metal

✓ Correct

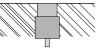
3 x sensor diamete non-metallic material e.g. epoxy

Sensor must be set up free-standing. Minimum distance to the sensor: approx. three times the diameter of the sensor

✓ Correct

Protruding sensor mounting (approx. half the sensor's length protruding)

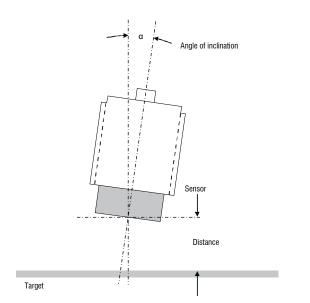
× False



Surrounding material attenuates sensor in the standard version; Measurement not possible.

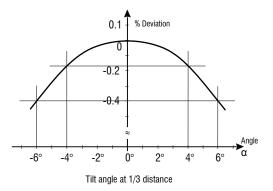
Tilt angle and measuring signal

The non-contacting displacement measuring system eddyNCDT is often used because of its excellent linearity and high resolution. This high resolution is achieved with right angle position, only. Sometimes an exact right angle mounting of the sensor to the target is difficult or impossible. In this case, the measured values deviate marginal from values, measured in right angle position. Hence it is important to know the influence to the measuring signal if the sensor is tilted. The following graphs show the influence to themeasuring signal of a tilted sensor.



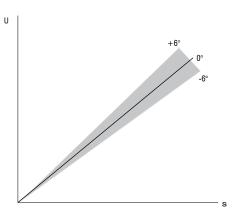
A permanent tilt angle can already be lodged at the controller with the 3-point linearisation. This avoids an influence of this tilt angle to the signal.

Tilt angles, the controller not linearised for, cause deviations of the measured values in comparison to right angled measurements.

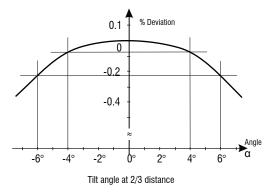


The extent of deviation is different fromsensor to sensor. These diagrams were taken with a U6 sensor and aluminium target. The diagrams show, that an inclination of ± 4 degrees can be accepted and neglected in most applications.

A tilt angle of more than 6 degree is rather possible with unshielded sensors than with shielded, but should be avoided. In principle, only a special linearised sensor provides a precise signal.



Example: Tilt a sensor 6° with 3 mm measuring range, means a deviation of 5 μm at 2/3measuring distance.



Resolution of displacement measurement systems

Definition of terms

The resolution is a measure of the fineness with which a change of displacement is reliably detected by a measurement system and the clear distinctive feature of two measurement values that are close to each other. Such displacements can only be measured with high complexity, because temperature effects, vibrations and other mechanical influences might disturb within measurement arrangement. Consequently, the signal-to-noise ratio is used in determining the resolution of the respective measurement system. The signal-to-noise ratio describes the level difference between the useful and interfering components of a signal.

Interfering component of a signal - thermal noise

The main constituents of the interfering component in a signal are the sum of the thermal noise of the measurement system including sensor cable, external interference effects and the residual ripple of the supply voltage. The principal component is caused by noise in the electronics. Due to the thermal movement of electrons in an electrical resistance, a noise process is produced which is described by.

the noise power density: $\frac{dP_r}{df} = 4k_BT$

 $k_{_B}$ = Boltzmann constant (1.3806504·10-23 J/K) T = absolute temperature

Measurement technology, effective noise voltage and RMS

For the random signals, electrical measurement technology makes use of descriptive quantities which can be derived from the electrical measurement quantities of voltage or power. This is based on the assumption that the mean of the observed signals is zero, i.e. they have no constant component as they vary about the value "0". Then the quadratic mean is equal to the variance. If the root of the variance is then taken, the dispersion is obtained which in turn describes the effective noise voltage. The dispersion or effective noise voltage is measured with an instrument which measures the effective value. Instruments from the English-speaking regions also use the term RMS (Root Mean Square, i.e. root of the squared mean) for the effective noise voltage.

The power developed across a resistance is termed as the noise power P_n and is described by

the equation $P_n = \frac{V_{n,ms}^2}{R}$

If the thermal noise on a resistance or system is measured with an RMS instrument, it must be taken into account that the instruments are restricted in their bandwidth (upper frequency response - lower frequency response).

Consequently, instead of acquiring the infinite variance, only an extract of it is obtained. The RMS noise voltage can therefore be quoted as follows: The noise voltage is then dependent on the absolute temperature and the bandwidth considered.

Resolution and signal amplification

The theoretical infinite resolution is in practice limited by temperature effects and the bandwidth. Amongst the temperature effects there is also the response time of the electronics during which the measurement device reaches the operating temperature by self-heating. That process is necessary in order to obtain reproducible measurement resultS. However, the noise voltage is inevitably increasing with the temperature.

As a rule, minor movements are associated with high speed. A corresponding high frequency response is necessary in order to detect the high speed. For measurement devices, a high frequency leads to increased noise voltage and reduced resolution.

Systems with non-linear characteristics, such as for example the eddyNCDT are linearised through circuitry. The larger gain required here for an increasing measurement distance also increases the noise voltage. Capacitive displacement measurement systems which exhibit an inherently linear characteristic have better prerequisites with regard to resolution.

Static or dynamic measurement

The resolution is given separately as static and dynamic values in the technical data on displacement measurement systems. One speaks of a static resolution when it can be assumed that the measurement object or the sensor is at a standstill. In the technical data tables this is occasionally quoted with the footnote $f \le 1$ Hz or $f \le 1$ OHz. The dynamic or effective resolution is related to the application and is always subject to a footnote regarding the frequency response. If there is no differentiation between statistic and dynamic, it is to be assumed that the statistic value is given which appears to be the better one.

Micro-Epsilon's measurement methods for determining the resolution.

The signal-to-noise ratio is determined using the following methods at three different distances (SMR, CMR and EMR) in the enclosed EMC cabin to avoid ambient effects, such as transmitter systems

1. RMS measurement

The frequency response of the digital multimeter (DMM) is 150kHz. The output voltage of the respective measurement system is amplified by a factor of 100 with an AC amplifier. This voltage is passes through an RC low-pass filter, the output of which is connected to DMM. The filter frequencies of the RC low-pass filters of the 1st order are 16Hz, 150Hz, 1.4kHz, 14.92kHz and 148.7kHz. An AC measurement without amplifier and low-pass filter is then made to determine possible residual carriers, etc.

 $V_{n,rms} = \sqrt{4 \cdot k_B} \cdot T \cdot R \cdot \Delta f$

2. Measurement of the noise peak value (V_{pp}) with the oscilloscope. The measurements are carried out with a digital storage oscilloscope. The measurement setup corresponds to the method for the RMS measurement. Then, also here an AC measurement without amplifier and low-pass filter is carried directly on the output. The assignment of LP filter frequency and time-base on the oscilloscope:

 16Hz/200ms
 150Hz/20ms

 1.4kHz/2ms
 14.92kHz/200μs

 148.7kHz/20μs
 without LP/20μs

3. Measurement of the noise peak value $(V_{\mbox{\tiny pp}})$ with the oscilloscope in the envelope-curve mode.

With this measurement, 128 measurement runs are recorded and displayed simultaneously. Isolated peaks and freak values also contribute fully to the measurement. This measurement also enables low-frequency noise to be acquired which otherwise would not be detected.

4. Measurement using LF spectrum analyser.

This measurement is also carried out. The spectrum in the range of the respective signal bandwidth is recorded here as well as the spectrum with multiples of the respective carrier frequency. It is decisive for the quality of the measurement that it occurs with adaptation of the power, i.e. the output resistance of the controller is equal to the input resistance of the spectrum analyser.

Calculation of the resolution of the noise voltage

As briefly illustrated at the start, the resolution is given separately as static and dynamic values in the technical data on displacement measurement systems. The resolution can be calculated from the noise voltage using the following formula:

$$Resolution_{rms}[mm] = \frac{V_{n,rms}[V]}{V_{Output, MR}[V]} \cdot MR[mm]$$

 $\begin{array}{lll} V_{n,\text{eff}} & = \text{effective noise voltage} \\ V_{\text{Output, MR}} & = \text{output voltage of the measuring range} \\ \text{MR} & = \text{measuring range of the sensor} \end{array}$

RMS value or peak-peak value

With a standard deviation of 1 σ (sigma) the RMS value is obtained in the Gaussian normal distribution. For signal components with a higher amplitude the probability that they are present in the signal decreases. For practical considerations a limit of $\pm 3 \sigma$ is assumed. According to this, the signal is located in this region with a confidence level of 99.7%. In order that resolutions, RMS or peak-peak, can be compared against one another, the following rule of thumb can be used:

Peak-peak value $V_{DD} = 6 \cdot RMS$ value $[\pm 3 \sigma]$.

The figure for the noise voltage or resolution as the RMS or peak-peak value depends on the objectives followed and has no influence on the actual resolution of a displacement measurement system. RMS values convey better values at first glance and are therefore the reason for frequent use in the technical data.

Conclusion

The resolution of displacement measurement systems is measured using two different methods. The background to both measurements is the measurement of the noise voltage. The most common method is the effective measurement which is usually quoted as RMS (Root Mean Square) in technical documentation. Quoting the resolution as a peakpeak value is rare, because the values obtained appear subjectively less favorable than for the RMS measurement.

Whether a manufacturer quotes the resolution as the RMS or peakpeak value depends on his objectives. It does not have any influence on the actual resolution of a displacement measurement system. Micro-Epsilon normally uses the RMS value for figures in the data sheet and identifies this with the note @RMS.

When considering technical data, it is decisive that RMS values and peak-peak values are only compared like with like. For the conversion the rule of thumb can be used the following formula: Peak-peak value = $6 \cdot \text{RMS}$ value (at±3 σ).

Required target thickness

The principle of eddy current displacement measurement requires a minimum thickness for stable results. This minimum thickness depends on the target material used and the sensor frequency. The sensor generates an alternating electromagnetic field which penetrates the target. Eddy currents beeing formed in the target cause a secondary magnetic field which attenuates the primary field.

Skin or penetration depth

Electromagnetic fields are attenuated on entering an electrically or magnetically conducting material. The reduction in the field strength and therefore the current density is accompanied by losses which occur in the vicinity of the material surface. The characteristic length at which the current density reduces to the value 1/e or to 37% is known as the skin depth(see Fig. 2).

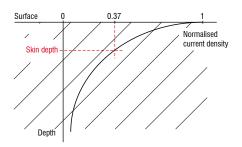
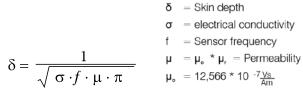


Fig. 2: Current density distribution in the target

Calculating the skin depth

The skin depth can be calculated with the following formula (it applies to the ideal case of a plane boundary layer and an infinitely extended object).

You can determine the permeability for some materials from Fig. 3. Or you can read off the skin depth directly from Table1.



| T | Skin depth in μ m at | | | | |
|------------------|--------------------------|------|--|--|--|
| Target material | 250kHz | 1MHz | | | |
| Aluminium | 168 | 84 | | | |
| Lead | 459 | 230 | | | |
| Gold | 149 | 74 | | | |
| Graphite | 2700 | 1350 | | | |
| Copper | 134 | 67 | | | |
| Magnesium | 209 | 104 | | | |
| Brass | 249 | 124 | | | |
| Nickel | 27 | 14 | | | |
| Permalloy | 4 | 2 | | | |
| Phosphor Bronze | 302 | 151 | | | |
| Silver | 130 | 65 | | | |
| Steel DIN 1.1141 | 23 | 12 | | | |
| Steel DIN 1.4005 | 55 | 27 | | | |
| Steel DIN 1.4301 | 848 | 424 | | | |

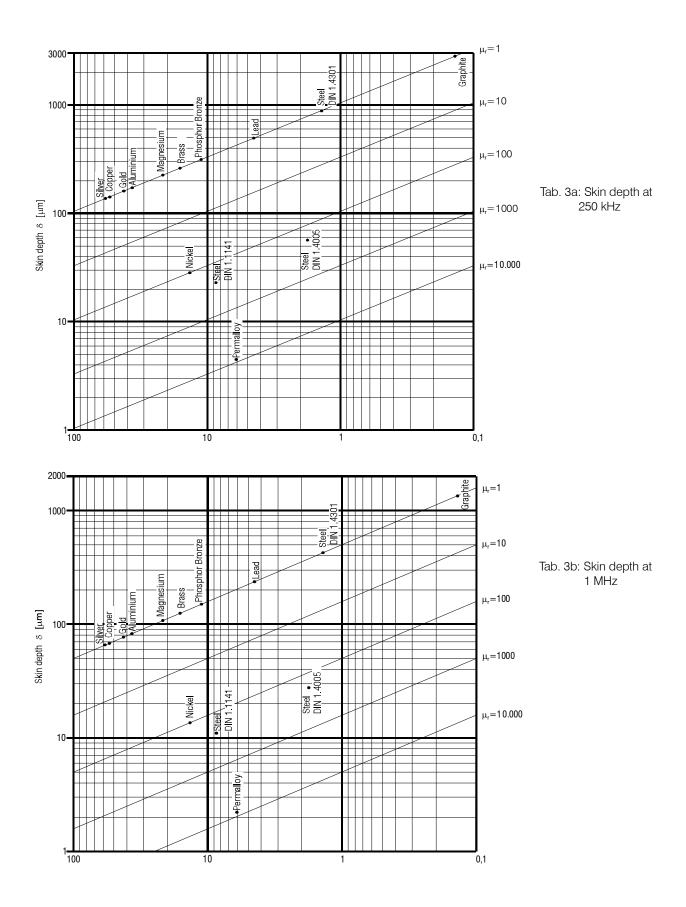
Tab. 1: Various skin depths

Calculating the minimum thickness

To calculate the minimum thickness of a material, take the appropriate skin depth from Table 1 or read off the skin depth from Fig. 3. Then you find the minimum thickness with the approximation value fromTable 2. This calculation only applies when using a sensor with a frequency of 250kHz or 1MHz.

| Measurement application | Minimum target thickness | | |
|---|--------------------------|--|--|
| Object detection (without displacement measurement) | "Skin depth" x 0.25 | | |
| Displacement measurement at approx. constant (room)temperature | "Skin depth" x 1.00 | | |
| Displacement measurement with changing temperature | "Skin depth" x 3.00 | | |
| Thickness measurement with two opposing sensors | "Skin depth" x 6.00 | | |

Tab. 2: Approximation values for simple determination of the minimum thickness



High performance sensors made by Micro-Epsilon



Sensors and systems for displacement and position



Optical micrometers, fibre optic sensors and fibre optics



Sensors and measurement devices for non-contact temperature measurement



Colour recognition sensors, LED analyzers and colour online spectrometer



2D/3D profile sensors (laser scanner)



Measurement and inspection systems



MICRO-EPSILON Headquarters Koenigbacher Str. 15 · 94496 Ortenburg / Germany Tel. +49 (0) 8542 / 168-0 · Fax +49 (0) 8542 / 168-90 info@micro-epsilon.com · **www.micro-epsilon.com** MICRO-EPSILON UK Ltd. No.1 Shorelines Building · Shore Road · Birkenhead · CH41 1AU Phone +44 (0) 151 355 6070 · Fax +44 (0) 151 355 6075 info@micro-epsilon.co.uk · www.micro-epsilon.co.uk